

<b>Notice of References Cited</b>	Application/Control No. 10/631,976	Applicant(s)/Patent Under Reexamination GRAF, STEFAN	
	Examiner McDieunel Marc	Art Unit 3661	Page 1 of 2

**U.S. PATENT DOCUMENTS**

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Name	Classification
	A	US-6,356,806 B1	03-2002	Grob et al.	700/245
	B	US-6,341,246 B1	01-2002	Gerstenberger et al.	700/245
	C	US-6,408,225 B1	06-2002	Ortmeier et al.	700/254
	D	US-6,466,844 B1	10-2002	Ikeda et al.	700/245
	E	US-6,556,891 B2	04-2003	Hietmann et al.	700/245
	F	US-6,587,749 B2	07-2003	Matsumoto, Kazunori	700/245
	G	US-6,615,112 B1	09-2003	Roos, Eberhard	700/254
	H	US-6,678,582 B2	01-2004	Waled, El-Houssaine	700/245
	I	US-6,853,881 B2	02-2005	Watanabe et al.	700/264
	J	US-6,776,722 B2	08-2004	De-Gol, Gino Daniel	472/59
	K	US-6,804,580 B1	10-2004	Stoddard et al.	700/248
	L	US-6,807,461 B2	10-2004	Kneifel et al.	700/248
	M	US-			

**FOREIGN PATENT DOCUMENTS**

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Country	Name	Classification
	N					
	O					
	P					
	Q					
	R					
	S					
	T					

**NON-PATENT DOCUMENTS**

*		Include as applicable: Author, Title Date, Publisher, Edition or Volume, Pertinent Pages)
	U	Blmann, Realistic robot simulation: Multiple instantiating of robot controller software, 2002, IEEE, pp. 1149-1198
	V	Afzulpurkar et al., Adaptive linear robot control for tracking and grasping a dynamic object, 2002, IEEE, pp. 578-583
	W	Agrawal et al., A new laboratory simulator for study of motion of free-floating robots relative to space targets, 1996, IEEE, pp. 627-653
	X	Swevers et al., An integrated friction model structure with improved presliding behavior for accurate friction compensation, 2000, IEEE, pp. 675-686

\*A copy of this reference is not being furnished with this Office action. (See MPEP § 707.05(a).)  
Dates in MM-YYYY format are publication dates. Classifications may be US or foreign.

<b>Notice of References Cited</b>	Application/Control No. 10/631,976	Applicant(s)/Patent Under Reexamination GRAF, STEFAN	
	Examiner McDieunel Marc	Art Unit 3661	Page 2 of 2

**U.S. PATENT DOCUMENTS**

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Name	Classification
	A	US-			
	B	US-			
	C	US-			
	D	US-			
	E	US-			
	F	US-			
	G	US-			
	H	US-			
	I	US-			
	J	US-			
	K	US-			
	L	US-			
	M	US-			

**FOREIGN PATENT DOCUMENTS**

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Country	Name	Classification
	N					
	O					
	P					
	Q					
	R					
	S					
	T					

**NON-PATENT DOCUMENTS**

*		Include as applicable: Author, Title Date, Publisher, Edition or Volume, Pertinent Pages)
	U	Kostin et al., Modeling of Dynamics of industrial robots with flexible electric drives, 1997, IEEE, pp. 275-278
	V	
	W	
	X	

\*A copy of this reference is not being furnished with this Office action. (See MPEP § 707.05(a).)  
Dates in MM-YYYY format are publication dates. Classifications may be US or foreign.